

Index

a

- Advanced process control (APC) 554
- Advanced regulatory control (ARC) 554
- Application 497
 - chemical reactor 528
 - control simulation 508, 539, 544
 - controller tuning 508, 544
 - distillate concentration control 501, 508
 - flue gas oxygen concentration control 529
 - furnace load control 501
 - gas heated furnace 528
 - petrochemical distillation column 499
 - predictive constrained linear MIMO control 498, 515, 527
 - pressure-compensated temperature control 501, 508, 517
 - pressure control 501, 508, 517, 523
 - real-time control 511, 523, 549
 - stripping column 515
 - temperature control 529

c

- Cascade control 581
 - application 478, 505, 509
- Case study
 - ammonium concentration control 489
 - distillate composition control 321
 - distillation column 318
 - forced heating and free convective cooling 375
 - heat exchanger 131, 362
 - hot air blower 458
 - injection molding machine 468
 - level control 348, 426
 - linear MIMO predictive control 321
 - nitrate concentration control 489
 - PFC 437
 - predictive linearized control 430

- predictive multicontroller 374
 - predictive multimodel control 372
 - predictive multiparameter control 372
 - predictive nonlinear control 429
 - predictive on–off control 132, 481
 - process identification 459
 - temperature control
 - 131, 370, 375, 460, 473
 - two-tank pilot plant 424
 - two-tank plant 348
 - wastewater plant 477, 488
 - wastewater quality control 477, 488
- Computational effort reduction
 - blocking technique 176, 182–183, 580
 - coincidence points 179, 183, 580
 - cost function 183
 - Constraint/limit
 - application 503, 518, 529, 541
 - cost function extension 198
 - end-point constraint 213
 - feasible solution 576
 - hard constraint 198, 206, 502, 575
 - physical constraints 193
 - prioritization 578
 - soft constraint 198, 503, 518, 575
 - typical constraint 194

- Controlled variable 4
 - application 502, 529

d

- Dead time (time delay) 30
- Decoupling (static) 300
 - by a postcompensator 303, 325
 - by a precompensator 301, 323
 - by a precompensator and a postcompensator 304, 326
- Decoupling of a MIMO process 297
 - by changing the control error weighting factors 315

- by control-error-dependent weighting factors 316
 - by slowing the reference signal change 312
 - by using a dynamic compensator 308
 - using a static compensator 300, 323
 - Difference operator 38
 - Disturbance
 - measurable 29, 36
 - unmeasurable 29, 36
 - Disturbance model 29, 36, 41
 - application 504, 519, 533
 - Disturbance signal
 - measurable 10
 - nonmeasurable 10
 - Disturbance variable
 - application 518, 530
- e**
- Economic benefit 565
 - application 513, 525
- f**
- Fusion technique 355
- g**
- Gaussian validity function 356
- i**
- Impulse response/weighting function 33
- l**
- Linear MIMO predictive control
 - application 498, 515, 527
 - controller tuning 294
 - cost function 277
 - polynomial form (RST) 284
 - with matrix inversion (GPC) 278
 - Linear SISO predictive control
 - control function 158
 - controller tuning 172
 - cost function 135, 165, 205
 - disturbance feed-forward 188
 - disturbance/robustness filter 159
 - generalized predictive control (GPC) 135
 - multiparametric programming 200
 - polynomial RST form 145
 - quadratic programming 199
 - under constraints 202, 204
 - with end-point constraint 213
 - with end-point weighting 216
- m**
- Manipulated variable 4
 - application 502, 517, 529
 - future sequence 137
- Model
- disturbance model 29, 36, 41
 - input/output 29
 - linear 29
 - MIMO 252
 - nonlinear 383
 - nonparametric 31
 - parametric 36
 - process model 29
 - SISO 29, 136
 - state space 43
- n**
- Nonlinear predictive control 591
 - based on a multicontroller 360
 - based on a multimodel 359
 - based on a multiparameter model 360
 - based on the linearized model 422
 - multidimensional iterative optimization 410
 - suboptimal (constant control increments) 407
 - suboptimal (constant control signal) 406
 - using the one-dimensional solution 406
 - Nonlinear predictive equation
 - multimodel approach 359
 - multiparameter model approach 359
 - Nonlinear process model
 - LPV model 354
 - multimodel 355
 - multiparameter model 358
 - with direction-dependent parameters 354
 - with signal-dependent parameters 354
 - Nonparametric model
 - linear SISO 31
 - nonlinear SISO 384
 - Nonparametric model (linear SISO) 31
 - finite impulse response (FIR) 32
 - finite step response (FSR) 33
 - Nonparametric model (nonlinear SISO)
 - Hammerstein series 384
 - Volterra series 384
- o**
- On–off control
 - nonpredictive with hysteresis 105, 480
 - nonpredictive without hysteresis 104
 - predictive 103

p

- Pairing of controlled and manipulated variables 287
 - RGA method 287, 290
- Parameter estimation
 - LS estimation 336
 - of predictive equation 335
 - of the process model 336
- Parametric model
 - difference equation 37
 - linear MIMO 252
 - linear SISO 36
 - nonlinear SISO 385–386, 388
 - pulse-transfer function 37
- Parametric model (linear MIMO)
 - CARIMA matrix fraction model 254
 - CARIMA state space model 258
 - CARMA matrix fraction model 252
 - CARMA state space model 256
- Parametric model (linear SISO)
 - CARIMA (ARIMAX) 51
 - CARMA (ARMAX) 41, 48
 - incremental 42
 - state space model 43
- Parametric model (nonlinear SISO)
 - bilinear 389
 - block-orientated 386
 - cascade 385
 - generalized Hammerstein 387, 389
 - linear-in-parameters 388
 - NARMAX 390
 - parametric Volterra model 389
 - simple Hammerstein 385
 - simple Wiener 386
- PI(D) control 221
- PI(D) controller
 - discretization of continuous form 240
 - Kuhn’s T-sum rule 241
 - set point weighting 242
 - Åström and Hägglund’s tuning rules 242
- Prediction
 - forced response 12, 59, 73, 81, 97, 100, 136, 274
 - free response 12, 59, 73, 81, 97, 100, 136, 274
 - of disturbance 57, 423
- Predictive control
 - cascade control 581
 - controller tuning 17, 151, 566
 - cost function 6, 13, 506, 570, 572
 - future trends 585
 - GPC 138, 278
 - implementation 559, 561, 566
 - long-range optimal 11
 - of linear MIMO processes 251
 - of linear SISO processes 135
 - of nonlinear SISO processes 406
 - one-step-ahead optimal 11
 - PFC 437
 - practical aspects 553
- Predictive equation
 - based on MIMO 271
 - based on the pulse-transfer function 64
 - in the case of autoregressive additive noise 74
 - in the case of nonautoregressive additive noise 81
 - in the presence of measurable disturbance 78
 - incremental 397, 405
 - nonincremental 392
 - of Hammerstein series 392
 - of the first-order model 65
 - of the generalized Hammerstein model 394, 401
 - of the Hammerstein series 398
 - of the impulse response model 56
 - of the parametric Volterra model 396, 403
 - of the second-order model 68
 - of the state space model 93
 - of the step response model 61
 - of the Volterra series 400
 - of Volterra series 393
- Predictive equation estimation
 - based on one step ahead 337
 - long-range optimal (LRPI) 339
 - multistep ahead (MSPI) 344
- Predictive functional control (PFC)
 - constraint handling 454
 - of a first-order linear process 443
 - of a nonlinear process with signal-dependent parameters 457
 - of a process with dead time 449
 - of a second-order linear process 446
 - of the LPV model 457
 - reference trajectory 438
 - with disturbance feed-forward 451
- Predictive on–off control
 - gap control 118, 126, 481–482
 - set point control 107, 473
 - start-up control 112, 473, 475
- Predictive on–off control algorithm
 - limit-violation-time-point-dependent cost function 121

- using genetic optimization 110, 118
 - using quasi continuous-time optimization 119
 - using the online start-up strategy 124
 - using the selection strategy 108
 - Predictive PI control 222
 - long-range horizon algorithm 224
 - of a first-order process with dead time 225
 - one-step-ahead algorithm 223
 - Predictive PI(D) control
 - equivalence with GPC 234
 - robust Smith predictor 246
 - robustifying filter 245
 - set point weighting 243
 - structure 222
 - tuning 240
 - Predictive PID control 221, 228
 - long-range horizon algorithm 230
 - of a second-order process with dead time 231
 - one-step-ahead extended horizon algorithm 229
 - Predictive SISO linear control
 - cost function 137
 - using matrix inversion (GPC) 138
 - Predictive transformation
 - by repeated substitution 65
 - by solving the Diophantine equation 70, 260, 394
 - with filtering of the input and output signals 84
 - with the matrix calculation method 88
 - Process identification 336, 562, 585
 - application 504, 531
 - Process model
 - application 504, 519, 530
- r**
- Receding horizon strategy 10
 - Reference signal 4, 578
 - future values 3
 - reference trajectory 579
 - set point 578
 - set range 578
 - set range funnel 580
- s**
- Sampling time 30
 - Scaling of variables 290, 293, 572
 - Shift operator 32
 - State space model
 - linear MIMO 255
 - linear SISO 43
 - State space model (linear SISO)
 - incremental 43–44
 - minimal order 44
 - nonincremental 43
 - nonminimal order 48
 - State variable 43
 - Step response 35
- t**
- Three-level control
 - nonpredictive 489
 - predictive 489
 - Time delay (dead time) 30
- w**
- Weighting function/impulse response 33
- z**
- Zero-order holding 30