

Index

a

- AC current control
 - control loop gains 549
 - decoupling gains 559
- active damping 525, 559, 659
- admittance matrix 54, 636, 637, 645, 653, 655
- amplitude invariance 68
- average-current-mode control
 - current-loop amplifier 225
 - duty-ratio generation 224–226
- averaged state space 7, 60, 63, 71, 73, 129, 143, 146, 149, 153, 164, 165, 167, 170, 233, 234, 279, 287, 362, 363, 367, 372, 380
- average modeling 57, 60, 142

b

- Bode plot 86–88, 90, 91, 312, 316, 322, 326, 327, 471–473, 477, 479
- boost converter 6, 134, 136, 146, 148, 149, 167, 199, 201, 206, 211, 213, 215, 222, 238, 258, 321, 325, 345, 346, 365, 366, 397, 439, 447, 479
- power-stage 351, 352, 383, 387, 390, 397, 398, 410, 439, 440, 446, 447, 451, 457
- boundary conduction mode (BCM) 58, 157
- buck-boost converter 136, 138, 139, 149, 151, 170, 199, 202, 206, 207, 213, 215, 222, 227, 239, 249, 347, 368, 369, 372, 387, 469
- power-stage 352, 387

- buck converter 3, 6, 7, 14, 15, 19, 61, 64, 97, 126, 127, 131–133, 135, 137, 140, 142–144, 164, 176–181, 191, 197–202, 205, 209–211, 213, 215, 222, 225, 230, 239–242, 244–248, 251, 253, 254, 269, 272, 274, 279, 280, 282, 287–289, 291–293, 298, 301, 307, 308, 312, 315, 330, 345, 346, 348, 358, 365, 414, 417, 476
- power-stage 351, 377, 380, 386, 387, 390, 397–399, 405, 406, 410, 411, 413

c

- CLCL filter 112, 115
- complementary sensitivity function 27, 84, 92
- continuous conduction mode (CCM) 57
- control bandwidth
 - crossover frequency 92
 - RHP pole limitation 102
 - RHP zero limitation 86, 163
- control block diagram
 - generalized MIMO cascaded control 365
 - generalized MIMO closed loop 48, 452
- generalized MIMO impedance-based stability assessment 394
- generalized MIMO load interaction 391
- generalized MIMO source interactions 390

- control block diagram (*Continued*)
 generalized SISO cascaded control 33
 generalized SISO closed loop 178
 generalized SISO impedance-based stability assessment 12
 generalized SISO load interaction 38
 generalized SISO source interactions 173
 control delay, Padé approximation 108
 control design
 AC-current control 493
 coupled-inductor superbuck 64, 474
 DC-voltage control 493
 DDR boost converter 213, 215, 321
 DDR buck converter 174
 discrete-inductor superbuck 331
 PCM boost converter 258, 315, 325
 PCM buck converter 178, 247
 phase-locked loop 591
 controller implementations
 I controller 106, 108, 449, 451
 P controller 106
 PI controller 107, 226, 227, 271, 534
 PID controller 105, 271, 295, 449
 coupled inductor 19, 64, 65, 157, 160, 205, 219, 221, 330, 332, 475
 cross-couplings 45, 549, 557–560, 622, 664, 665, 683
 crossover frequency
 gain margin 13, 325
 phase margin 447, 457, 555, 556, 571, 576
 RHP pole limitation 89
 RHP zero limitation 325, 326
 current-fed converter
 boost converter 345
 buck-boost converter 347
 buck converter 342
 current-fed inverter 515
 non-inverting buck-boost converter 149
 quadratic buck converter 348
 sepic converter 347
 superbuck converter 372
 current-mode control
 average-current-mode control 225
 peak-current-mode control 190
 self-oscillation control 125, 231
- d**
 damping ratio, phase-locked loop 543
 d-channel 550, 603, 644, 645
 DC UPS, 36, 266, 278
 DC-voltage control 493, 507, 514, 520, 533, 549, 563, 598, 606, 639, 640, 645, 646, 656, 669, 692–694
 decoupling gains 497, 533, 549, 559, 561, 562, 633, 634, 644–646, 649, 664
 differential power processing 468, 469
 direct component 423
 direct-duty-ratio 57, 125
 control 8
 direct-on-time control 125, 127
 discontinuous conduction mode (DCM) 7, 57
 distributed MPP tracking 465
 dq-domain current control 622
 duality transformation 6, 9, 20, 341, 342, 358, 377, 485
 duty ratio 8, 27, 57, 62, 99, 101, 125, 128, 155, 163, 164, 174–176, 189, 190, 192–197, 199, 201–207, 209, 210, 213, 215, 218, 222, 223, 225, 226, 228, 231, 284, 351, 372, 379, 397, 404, 407, 411, 413, 415, 436, 441, 445, 446, 495, 551, 560, 612, 634, 635, 649, 651, 684, 690
 gain 176, 189, 194, 196, 260, 406
 dynamics 30, 32, 38, 48, 54, 92, 125, 212, 217, 267, 360, 364, 371, 408, 416, 437, 470, 499, 515, 518, 527, 536, 549, 550, 564, 592, 603, 637, 638, 640, 651, 652, 681, 687
 capacitance 426, 470
 modeling 7, 20, 45, 58, 66, 125, 189, 265, 355, 377, 403, 493, 681, 692
 resistance 426, 429, 446, 470, 474, 518, 519, 523

e

equivalent circuit

- canonical equivalent circuit
 - current-fed DC-DC converter 10, 43
 - three-phase AC-DC converter 10
 - three-phase DC-AC converter 10
- canonical equivalent circuit 8, 11
- voltage-fed DC-DC converter 9
- equivalent switching circuit (DC-AC) 508
- multiport network equivalent circuit (MISO)
 - three-phase voltage-input-current-output converter (Y) 500
 - three-phase voltage-input-voltage-output converter (G) 500
- multiport network equivalent circuit (SIMO) 87
- three-phase voltage-input-current-output converter (Y) 622
- three-phase voltage-input-voltage-output converter (G) 495
- two-port network equivalent circuit 28
- current-input-current-output converter 5
- voltage-input-current-output converter (Y) 189
- voltage-input-voltage-output converter (G) 268

error amplifier

- current-loop amplifier 225
- I-type 449
- PID-type 312, 447
- PI-type 226

f

feedback

- complementary sensitivity function 27
- loop gain 52, 84, 102, 300, 312, 321, 325
- robustness indices 95
- sensitivity function 93

fill factor 433

- fixed-frequency operation 126, 128, 142, 163, 164
- forbidden region 13, 14, 92–95
- frequency response 4, 5, 16, 77, 86, 89, 105–108, 114–117, 226, 227, 249, 258, 259, 397, 450–452, 455–459, 471, 503, 505, 514, 523, 539, 542, 569, 589, 608, 653, 690, 692
- measurement 583, 598
- full-order model 615, 633, 645, 648, 664
- full-power processing 469

g

- gain-bandwidth product 102
- generalized modeling technique 126, 129
- G parameter 5
- grid-feeding operation 11, 18
- grid-forming operation 18, 50
- grid-parallel operation 17, 50, 53
- grid-supporting operation 509
- grid-voltage feedforward 533, 562, 587, 596, 599, 610, 611, 614, 616, 617, 619, 623, 624, 626, 628, 648, 651, 653, 655, 656, 674, 675

h

- harmonic operation 196, 320

i

- ideal input admittance 174, 237, 242, 305
- ideal input impedance 101, 173, 174, 240, 361, 391, 393
- ideal input-output transfer function 31, 33, 50
- ideal output admittance 392
- ideal output impedance 394
- ideal output-input transfer function 643
- impedance-based stability criterion 667
- impedance shaping 678
- input filter
 - LC filter 95, 112, 349

input-voltage feedforward 174, 194
 instability 14, 16, 179
 interaction
 load interaction 19, 38, 54, 176, 239,
 270, 390, 393
 source interaction 101, 173, 174,
 244, 269, 390, 392
 inverters 4, 15–18, 47, 50, 111, 351,
 432, 435, 465
 inverting buck-boost 137, 138
 irradiance 424, 432, 434, 507
 IV curve 426, 429–432, 434, 468

j

Jacobian matrix 60

k

K value 68, 87, 539

l

LC filter 95, 102, 111, 112, 181, 244,
 246, 345, 349, 674
 LCL filter 111, 113, 525, 528, 648, 653,
 655, 656
 L filter 550
 linearized model, phase-locked-
 loop 536, 591
 load effect 28, 189, 211, 250, 254, 255,
 266, 273, 502, 503, 521, 558, 577,
 620
 load-transient response 181
 loop gain
 controller 311
 design constraints 100
 gain-bandwidth product 102
 loop shaping 310

m

MATLAB code 500, 501, 526, 528
 maximum peak criteria (MPC) 94
 maximum power point (MPP) 4, 395,
 579
 tracking 432, 436, 437, 439, 444, 446,
 451, 453
 mode limit 190, 194, 196, 197, 199, 200,
 204, 228, 291, 319

model verification
 inverter output admittance 645, 646,
 656, 657, 668, 669
 inverter output impedance 16, 669,
 671, 674
 open-loop dynamics 499, 510, 527, 681
 modulator gain 31, 35, 97–99, 128, 129,
 321, 325, 551, 587, 616

n

negative incremental resistance 185,
 244, 361, 429, 482
 negative sequence component 544, 545
 non-inverting buck boost 139, 149,
 151, 347, 368, 387
 Nyquist plot 57, 87–90, 487
 Nyquist stability criterion 13, 20, 41,
 57, 87, 89, 95, 179, 271, 394, 482,
 574, 668, 672

o

open-circuit input admittance 270
 open-circuit input impedance 391,
 408, 413
 open-circuit output admittance 267,
 268
 open-circuit output impedance 177,
 215, 217, 221, 241
 open-circuit voltage 426, 430, 433, 434
 open-loop control block diagram 503,
 686
 open-loop transfer function 31, 35, 97,
 250, 500, 511, 521, 550, 587, 595,
 605, 641, 650, 688, 691
 output-current feedforward 177, 240,
 241, 395
 output filter
 LC filter 102
 LCL filter 111
 L filter 550
 output impedance 254
 output-voltage feedforward 394, 447

p

Padé approximation 108, 311, 543, 629
 passive damping 524, 620, 665

- peak current mode control
 CCM modeling 244
 comparator equation 290
 DCM modeling 222
 duty-ratio generation 224
 harmonic operation mode 190
 mode limit 190
 peak voltage mode control 403
 perturb and observe 432, 435
 perturbation frequency
 closed-loop converter 244
 design 437
 settling time 294
 phase-locked loop (PLL) 15
 photovoltaic (PV) cell
 constant current region 521
 constant power region 439
 constant voltage region 521
 current-voltage curve 517, 522
 dynamic resistance 435
 maximum power point (MPP) 521
 open-circuit voltage 430
 power-voltage curve 518, 576
 short circuit current 433
 photovoltaic (PV) generator
 MPP tracking 436
 power dynamics 461
 stability 465
 photovoltaic inverter 509, 523, 545,
 567, 574, 598, 605, 625, 626, 628,
 646, 656
 PI controllers 106, 107, 226, 227, 278,
 534, 538, 548, 590, 642, 691
 polar plot 86, 87, 89
 positive sequence component 535, 545
 power invariance 68
 pseudo-random binary sequence 249, 504
- q**
 Q-channel 498, 501, 502, 560, 591, 609
 quadrature component 11, 68
 quality factor (Q) 113, 146, 149, 153
- r**
 real-time simulator 542, 543, 575, 625,
 627, 646, 656, 692
- rectifier 11, 33, 37, 42, 44, 47, 69, 70,
 494, 495, 500, 515, 533, 566, 681,
 684, 686, 687, 689–691, 693, 694
 reduced-order dynamics 633
 remote sensing 277, 279, 304, 306, 307,
 309, 310
 resonant frequency 81, 102, 112, 113,
 181, 304, 312, 321, 322, 326, 361,
 368, 395, 447, 524, 553, 657
 resonant peaking 110
 RHP pole, control design constraint due
 to RHP pole 102
 RHP zero, control design constraint due
 to RHP zero 102
 Ridley model 249
 RMS invariance 68
 Routh array 85, 87, 88, 159
 Routh Hurwitz 84–86, 218, 375
- s**
 second-order system estimate
 damping factor estimate 80, 541
 feedback-loop crossover
 frequency 102
 undamped natural frequency
 estimate 149, 541
 settling time 96, 98, 99, 247, 294, 315,
 321, 329, 444, 446, 450, 453–456,
 459, 534, 541, 571, 692, 693
 short-circuit current 426, 433, 434, 579
 short-circuit input admittance 211,
 215, 217, 221, 237, 241, 305
 short-circuit input impedance 15, 242,
 243, 246, 306
 short-circuit output admittance 392,
 408, 413
 short-circuit output impedance 394
 Simulink average model
 DRR-controlled buck converter 254
 PCM-controlled buck converter 253
 PWM modulator 288
 Simulink switched model
 closed-loop converter 285
 DDR-controlled buck converter 284
 input filter 285
 output filter 507, 525

- Simulink switched model (*Continued*)
- PCM-controlled buck converter 284
 - PWM modulator 284
- single pole 79, 311
- single zero 78, 298
- small-signal modeling
- average mode 57
 - linearization, Jacobian matrix 60
 - buck converter example 61
 - conduction mode 57
 - coupled-inductor modeling 66
 - three-phase rectifier example 69
- solar cell 423–427, 429
- source effect
- source-affected transfer functions of PV inverter 474
- stability
- conditional stability 27
 - generalized Nyquist stability criterion 87
 - instability 305
 - Nyquist criterion 394
 - robustness indices 95
 - Routh array 87
 - Routh Hurwitz 86
 - unconditional stability 27
- state space 7–9, 59, 60, 63, 65, 73, 74, 76, 126, 130, 132–135, 138–140, 142–145, 147–149, 151, 152, 154, 157, 158, 160, 164, 165, 167, 168, 170, 171, 189, 193, 201, 209, 211–217, 219, 220, 222–224, 232, 234, 235, 279, 287, 288, 355, 360, 361, 363, 367, 370, 374, 378, 380, 384, 385, 388, 406, 411, 415, 418, 419
- averaging technique 57, 125
- step response
- AC current control 493, 559, 606
 - DC voltage control 493, 520
 - phase-locked loop 591, 609
- synchronous reference frame
- amplitude invariance 68
 - power invariance 9, 42
 - RMS invariance 68
- t**
- transfer function
- control-to-input transfer function 375, 472, 479, 480, 690
 - control-to-output transfer function 52, 83, 155, 211, 221, 273, 413, 472, 478–480, 518
 - input admittance 145, 148, 152, 167
 - input impedance 643
 - input-to-output transfer function 637, 643
 - output admittance 392, 637
 - output-to-input transfer function 643
- second-order transfer function 80
- single pole 79
- single zero 298
- transient performance
- indices 27, 96
 - load-transient response 95
 - settling time 329
- u**
- unbalanced grid voltages 543, 544, 577
- underdamped natural frequency
- phase-locked loop 80
- v**
- variable frequency control 7, 189
- voltage-fed inverter 111, 493–496, 498, 500, 502–506, 508, 516, 533, 548–553, 560, 563, 567, 587, 588, 591, 595, 596, 602, 610
- voltage-mode control 125, 231
- y**
- Y-parameters 29, 44, 249, 500
- z**
- Z-parameters 5, 29, 44, 355, 357