

Contents

Preface *XI*

List of Contributors *XIII*

1	Merging Technology with Biology	1
	<i>Ranu Jung</i>	
1.1	Introduction	1
1.2	NeuroDesign	2
1.3	The NeuroDesign Approach	3
1.4	Neuromorphic Control of a Powered Orthosis for Crutch-Free Walking	4
1.5	Frontiers of Biohybrid Systems	7
1.6	Chapter Organization	8
	References	9
2	Principles of Computational Neuroscience	11
	<i>Sharmila Venugopal, Sharon Crook, Malathi Srivatsan, and Ranu Jung</i>	
2.1	Introduction	11
2.2	Some Physiology of Neurons	12
2.2.1	Membrane Potential	13
2.2.2	Membrane Equivalent Circuit	15
2.2.3	Action Potential: Generation and Propagation	16
2.3	General Formalisms in Neuronal Modeling	18
2.3.1	Conductance-Based Hodgkin–Huxley Model for Action Potential Generation	18
2.3.2	Chemical and Electrical Synaptic Inputs	20
2.3.3	Cable Theory of Neuronal Conduction and Compartmental Modeling	21
2.3.4	Calcium and Calcium-Dependent Potassium Currents	22
2.3.5	Simplified Neuronal Models	23
2.4	Synaptic Coupling and Plasticity	24
2.4.1	Modeling Synaptic Plasticity	25
2.5	Computational Models of Neuronal Systems for Biohybrid Applications	27

2.6	Resources	27
	References	28
3	Neuromorphic Electronic Design	31
	<i>Francesco Tenore and Ralph Etienne-Cummings</i>	
3.1	Choices for Neuromorphic Circuits: Digital versus Analogue	31
3.2	The Breadth of Neuromorphic Systems	32
3.3	The Fundamental Processing Unit: The Neuron	33
3.3.1	Conductance-Based Modeling	35
3.3.2	Compartmental Modeling	36
3.3.2.1	The Dendritic Compartment: Home to the Synapses	37
3.3.2.2	The Somatic Compartment: Spike-Based Processing and the Integrate-and-Fire Model	38
3.3.2.3	The Axonal Compartment: Address-Event Representation	39
3.4	Sensing the Environment	40
3.4.1	Vision	41
3.4.2	The Silicon Retina	42
3.4.3	Audition	44
3.4.3.1	Silicon Cochlea Modeling	46
3.5	Conclusions	48
3.6	Resources	48
	References	49
4	Principles of Neural Signal Processing	53
	<i>Don H. Johnson</i>	
4.1	Introduction	53
4.2	Point Process Theory	53
4.2.1	Definition of a Point Process	53
4.2.2	Examples of Point Processes	55
4.2.2.1	The Poisson Process	55
4.2.2.2	Renewal Processes	56
4.2.2.3	Markov Point Processes	58
4.2.2.4	Non-Markovian Point Processes	58
4.2.3	Multiple Point Processes	59
4.3	Analyzing a Point Process	60
4.3.1	The Interval Histogram and Hazard Function	61
4.3.2	The PST Histogram	62
4.3.3	Characterizing Multiple Point Processes	63
4.4	Dynamic Neural Processing	64
4.5	Information Theory and Neural Signal Processing	66
4.5.1	Data Processing Theorem	67
4.5.2	Channel Capacity	68
4.5.3	Rate Distortion Theory	70
4.5.4	Application to Biohybrid Systems	72
4.6	Summary	73
	References	74

5 **Dynamic Clamp in Biomimetic and Biohybrid Living-Hardware Systems** 77

Ryan Hooper and Astrid A. Prinz

- 5.1 What is a Dynamic Clamp? 77
 - 5.1.1 The Digital Dynamic Clamp 80
- 5.2 Dynamic Clamp Performance and Limitations 82
- 5.3 Experimental Applications of Dynamic Clamp 83
 - 5.3.1 Example Application 1: Neuronal Gain Control 84
 - 5.3.1.1 Synaptic Background Noise Mechanism 84
 - 5.3.1.2 Synaptic Depression Mechanism 86
 - 5.3.2 Example Application 2: Constructing Artificial Neuronal Circuits 86
- 5.4 Dynamic Clamp System Implementations and Future 88
 - 5.4.1 Fundamental Considerations 88
 - 5.4.2 Recent and Future Implementations 90
- 5.5 Resources 91
 - References 92

6 **Biohybrid Circuits: Nanotransducers Linking Cells and Neural Electrodes** 95

Linfeng Chen, Jining Xie, Hargsoon Yoon, Malathi Srivatsan, Robert E. Harbaugh, and Vijay K. Varadan

- 6.1 Introduction to Neural–Electrical Interfaces 95
 - 6.1.1 Typical Types of Microelectrode Arrays 95
 - 6.1.2 Electric Circuit Model 97
 - 6.1.3 Requirements on Electrode Materials 98
 - 6.1.4 Applications of Nanotechnology 99
- 6.2 Neural Probes with Nanowires 99
 - 6.2.1 Metallic Nanowires for Neural–Electrical Interfaces 100
 - 6.2.2 Metal Oxide Nanowires for Neural–Electrical Interfaces 101
- 6.3 Microelectrode Arrays with Carbon Nanofibers 101
- 6.4 Microelectrode Arrays with Carbon Nanotubes 103
 - 6.4.1 Microelectrode Arrays with Random Carbon Nanotubes 103
 - 6.4.2 Microelectrode Arrays with Vertically Aligned Carbon Nanotubes 105
- 6.5 Microelectrode Arrays with Conducting Polymer Nanomaterials 106
- 6.6 Nanoelectrodes for Neural Probes 107
 - 6.6.1 Metal Nanoelectrodes 108
 - 6.6.2 Carbon Nanotube-Based Nanoelectrodes 109
- 6.7 Summary and Future Work 110
 - References 110

7 **Hybrid Systems Analysis: Real-Time Systems for Design and Prototyping of Neural Interfaces and Prostheses** 115

William Barnett and Gennady Cymbalyuk

- 7.1 Introduction 115
- 7.2 Technology 117
 - 7.2.1 dSPACE Boards 118

7.2.2	Introduction to Programming in Simulink	118
7.2.3	Library for Dynamic Clamp	120
7.3	Applications	125
7.3.1	Building Neuronal Models with Simulink for Real-Time Analysis	125
7.3.2	Propensity to Hazardous Dynamics of the Squid Giant Axon	128
7.4	Hybrid Systems Analysis in the Leech Heart Interneuron	130
7.4.1	Model Heart Interneuron	131
7.4.2	Hybrid Systems Analysis	132
7.5	Discussion	133
	References	136
8	Biomimetic Adaptive Control Algorithms	139
	<i>James J. Abbas</i>	
8.1	Introduction	139
8.1.1	Potential to Enhance Capabilities of Engineered Systems	139
8.1.2	Integrating Engineered Systems with Biological Systems	140
8.1.3	Focus on the Nervous System	140
8.2	Biomimetic Algorithms	141
8.2.1	Input/Output Models	141
8.2.2	Neurostructural Models: Models Based on Regional Neuroanatomy and Neurophysiology	143
8.2.3	Artificial Neural Network Models	144
8.2.4	Biophysical Models: Conductance-Based Models and Beyond	145
8.2.5	Central Pattern Generators	148
8.3	Discussion	151
8.4	Future Developments	152
	References	153
9	Neuromorphic Hardware for Control	157
	<i>Kevin Mazurek, R. Jacob Vogelstein, and Ralph Etienne-Cummings</i>	
9.1	Neuromorphic Hardware for Locomotion	157
9.1.1	A Biohybrid System for Restoring Quadrupedal Locomotion	159
9.1.2	Silicon Neural Network Design	159
9.1.3	Using the Chip for Locomotor Control	161
9.2	Neuromorphic Hardware for Audition	162
9.2.1	AER EAR Architecture	163
9.2.2	AER EAR Control Application	164
9.3	Neuromorphic Hardware for Vision	166
9.3.1	The Neuromorphic Imager (Silicon Retina)	167
9.3.2	Visual Tracking	168
9.3.3	Object Tracking Application	169
9.4	Conclusions	171
	References	172

10	Biohybrid Systems for Neurocardiology	175
	<i>Peter H. Veltink, Lilian Kornet, Simone C.M.A. Ordelman, Richard Cornelussen, and Rik Buschman</i>	
10.1	Introduction	175
10.2	Autonomic Neural Control of the Heart	176
10.2.1	Antagonistic Neural Control of the Heart	176
10.2.2	Reflexive Neural Control of the Heart	177
10.2.3	Hierarchical Neural Control of the Heart	178
10.3	Monitoring and Modulating the Autonomic Reflexive Control of the Heart	178
10.3.1	Sensing of Afferent Signals from and Efferent Signals to the Heart	180
10.3.2	Stimulation of the Parasympathetic Input to the Heart	182
10.3.2.1	Stimulation of the Cervical Vagus Nerve	182
10.3.2.2	Stimulation of the Autonomic Cardiac Innervation	185
10.3.3	Biohybrid Closed Loop Artificial Neural Control of the Heart	186
10.4	Conclusions	187
	References	187
11	Bioelectronic Sensing of Insulin Demand	191
	<i>Mathieu Raoux, Guilherme Bontorin, Yannick Bornat, Jochen Lang, and Sylvie Renaud</i>	
11.1	Sensor Technologies and Cell Therapy in Diabetes: a Life-Long Debilitating Disease	191
11.2	The Biological Sensor: Function of β -Cells and Islet	192
11.3	Automated Islet Screening and Bioelectronic Sensor of Insulin Demand	194
11.4	Closed Loop Exploration <i>In Vitro</i>	195
11.5	Methods	195
11.5.1	Cultures and MEA	195
11.5.2	Signal Conditioning and Spike Detection	196
11.6	Results	198
11.6.1	Recordings	198
11.6.2	Adaptive Detection	199
11.7	Conclusions	200
	References	201
	Index	203

