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Cover Image:

The cover image shows Jasmine robots prepared by Serge Kernbach, Marc Szymanski, Thomas Schmickl for the large-scale swarm experiment, for more information see Serge Kernbach, Dagmar Häbe, Olga Kernbach, Ronald Thenius, Gerald Radspieler, Toshifumi Kimura and Thomas Schmickl, "Adaptive collective decision-making in limited robot swarms without communication", *International Journal of Robotics Research*, 32(1), 35–55, 2013 and Serge Kernbach, Ronald Thenius, Olga Kernbach and Thomas Schmickl, "Re-embodiment of Honeybee Aggregation Behavior in an Artificial Micro-Robotic System", *Adaptive Behavior*, 17(3), 237–259, 2009.

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Library of Congress Card No.: applied for

British Library Cataloguing-in-Publication Data

A catalogue record for this book is available from the British Library.

Bibliographic information published by the Deutsche Nationalbibliothek

The Deutsche Nationalbibliothek lists this publication in the Deutsche Nationalbibliografie; detailed bibliographic data are available on the Internet at <http://dnb.d-nb.de>.

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Print ISBN: 978-3-527-41166-5

ePDF ISBN: 978-3-527-65955-5

ePub ISBN: 978-3-527-65954-8

mobi ISBN: 978-3-527-65953-1

oBook ISBN: 978-3-527-65952-4

Cover Design Adam-Design, Weinheim

Typesetting Thomson Digital, Noida, India

Printed on acid-free paper